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Homework 1 Solutions Instructor: Michael Mahoney Due 10/19/09 at 11:00AM Problem 1 In class we looked at random projections with entries drawn from N(0;1) (i.e. the standard normal distribution). In this problem we consider a random projection matrix entries of which are sampled from a discrete distribution symmetric about the origin.

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Solutions will be posted on the course website shortly after the due time. Homework 1 due January 19th by 5pm. Solutions to homework 1. Homework 2 due January 27th by 5pm. Solutions to homework 2. Homework 3 due February 7th by 5pm. Solutions to homework 3. Midterm due February 16th by 5pm. Solutions to Midterm. Homework 4 due February 28th by 5pm. Introduction to Robotics (CS223A) Homework #1 Solution (Winter 2007/2008) 1. A frame {B} and a frame {A} are initially coincident. Frame {B} is rotated about Y^ B by an angle θ , and then rotated about the new Z^B by an angle φ. Determine the 3 ×3 rotation matrix, A BR, which will transform the coordinates of a position

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Driving in Manhattan a State: suppose s
2States, then s = (street; avenue), where 1
street n;1 avenue m. Action: suppose a
2Actions(s), then a can be either of the following: move North if street < m move
South if street > 1 move East if avenue >
1 move West if avenue < n

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Problem 1 - Stanford University

Some Words about Reasonable Answers.

1. An answer to any problem is an estimate. As such, you should not express the answer with greater precision than is warranted by the problem statement and means used to obtain the solution.

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